

Test Means at Airbus Defence and Space,  
Military Aircraft business line

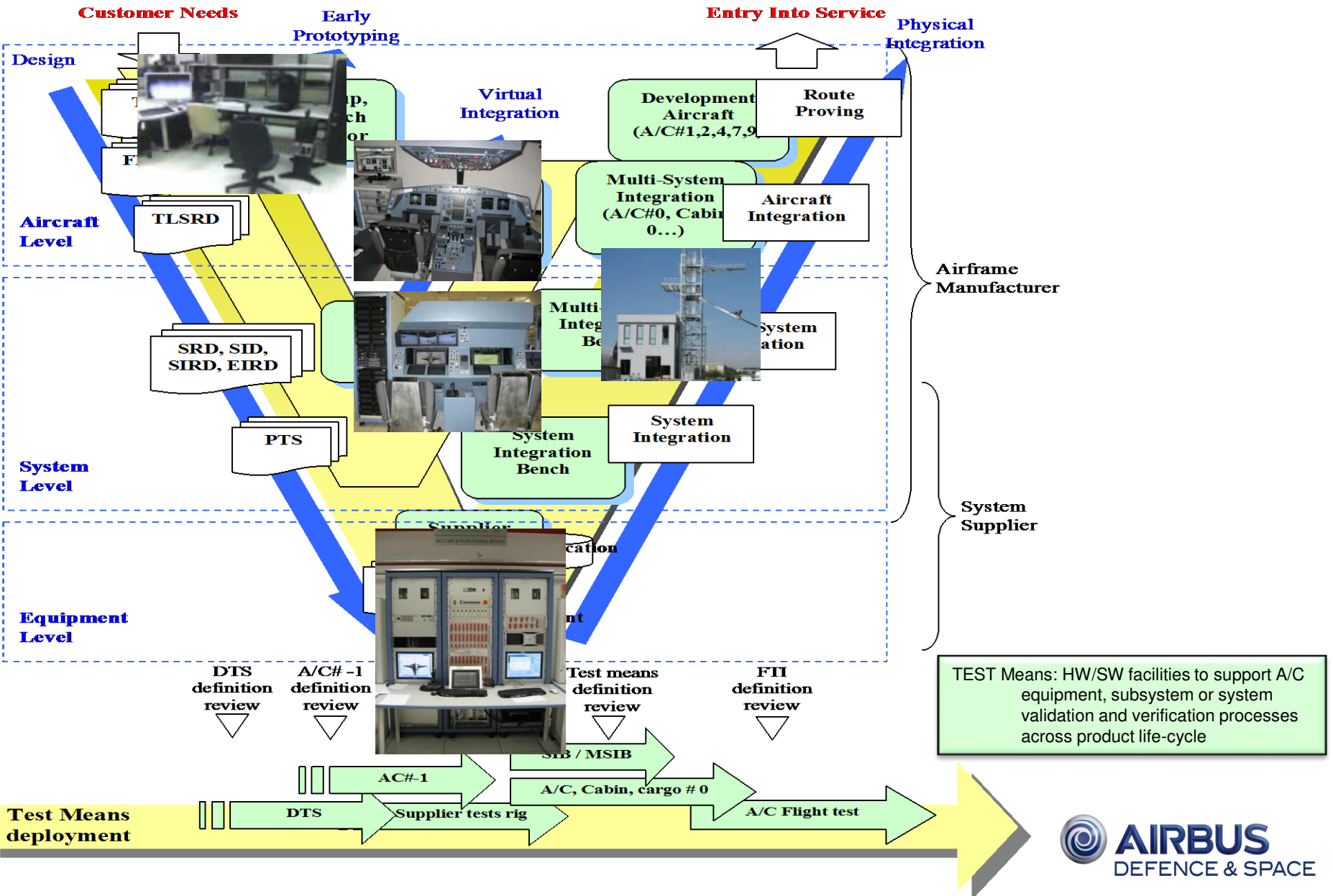
# Making Ada the Heart of an All- Encompassing Aircraft Test Life-Cycle

Industrial Presentation, Ada in Aerospace Session  
Ada Europe 2014, Paris

Javier Arroyo  
Test Systems

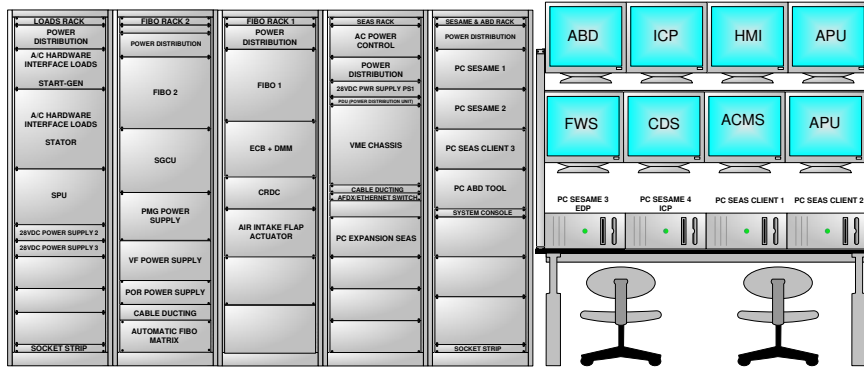
24 June 2014

# A/C Electronics Systems Development Life Cycle

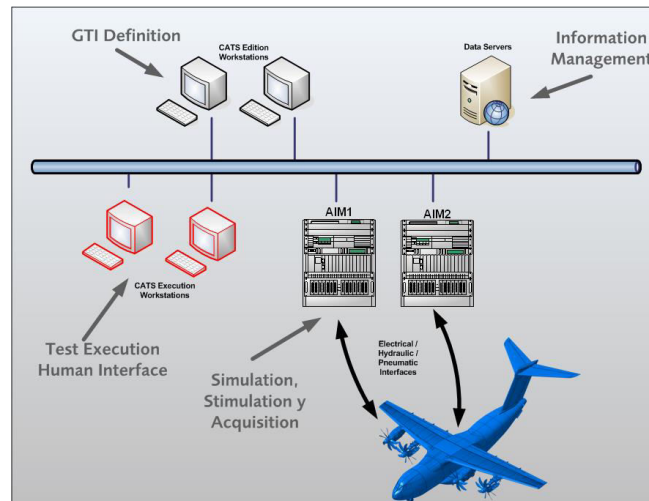


# Test Means Architecture

## SYSTEM INTEGRATION BENCHES



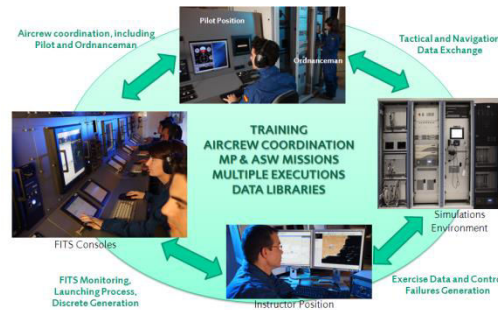
## FAL TEST SYSTEM



## Remarkable capabilities

- Common Aircraft Interface Core Module
- Manual and automatic aircraft interfaces
- Specific User Interface

# Test Facilities

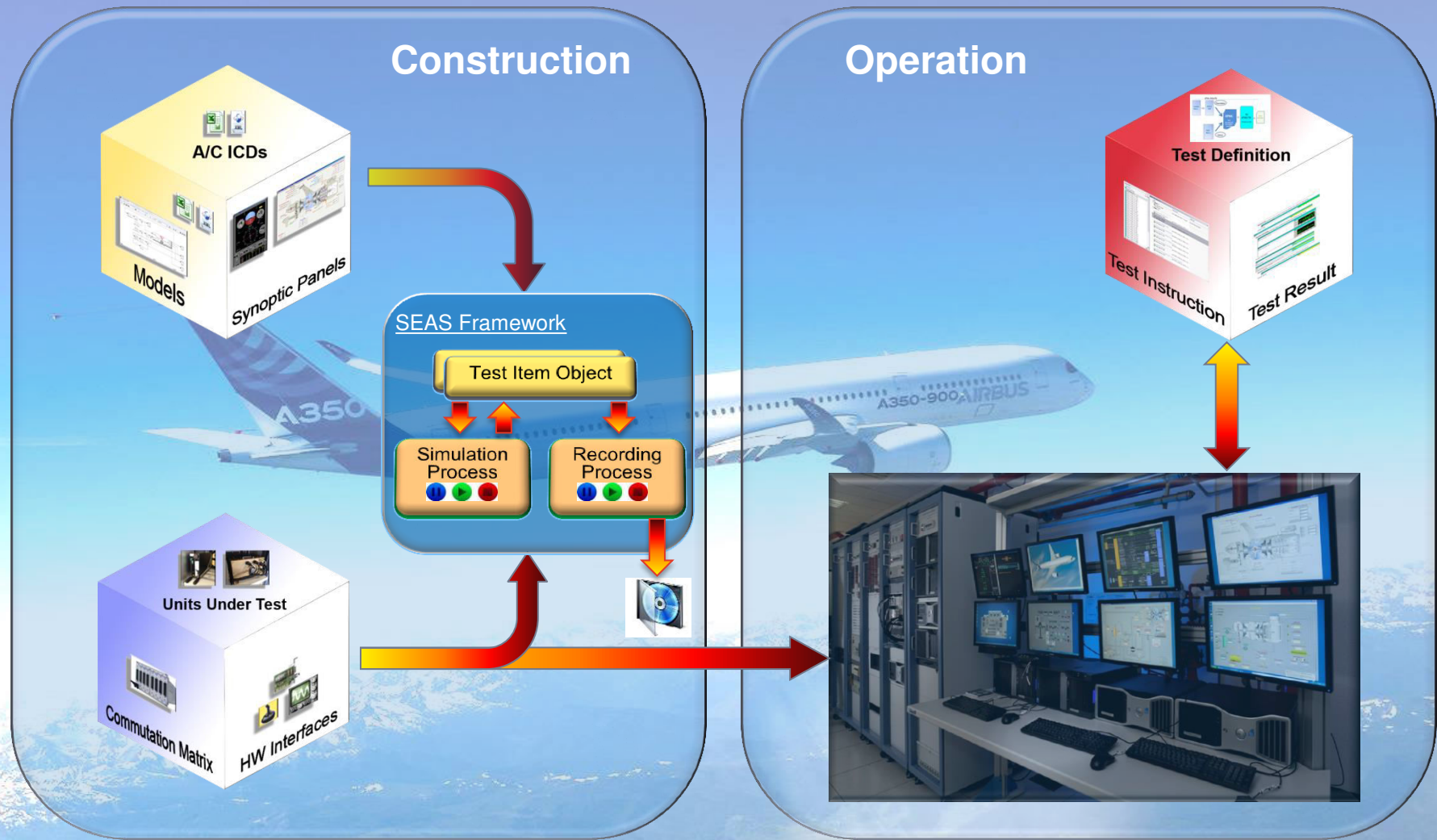


## A common solution applied over and over again to satisfy different needs

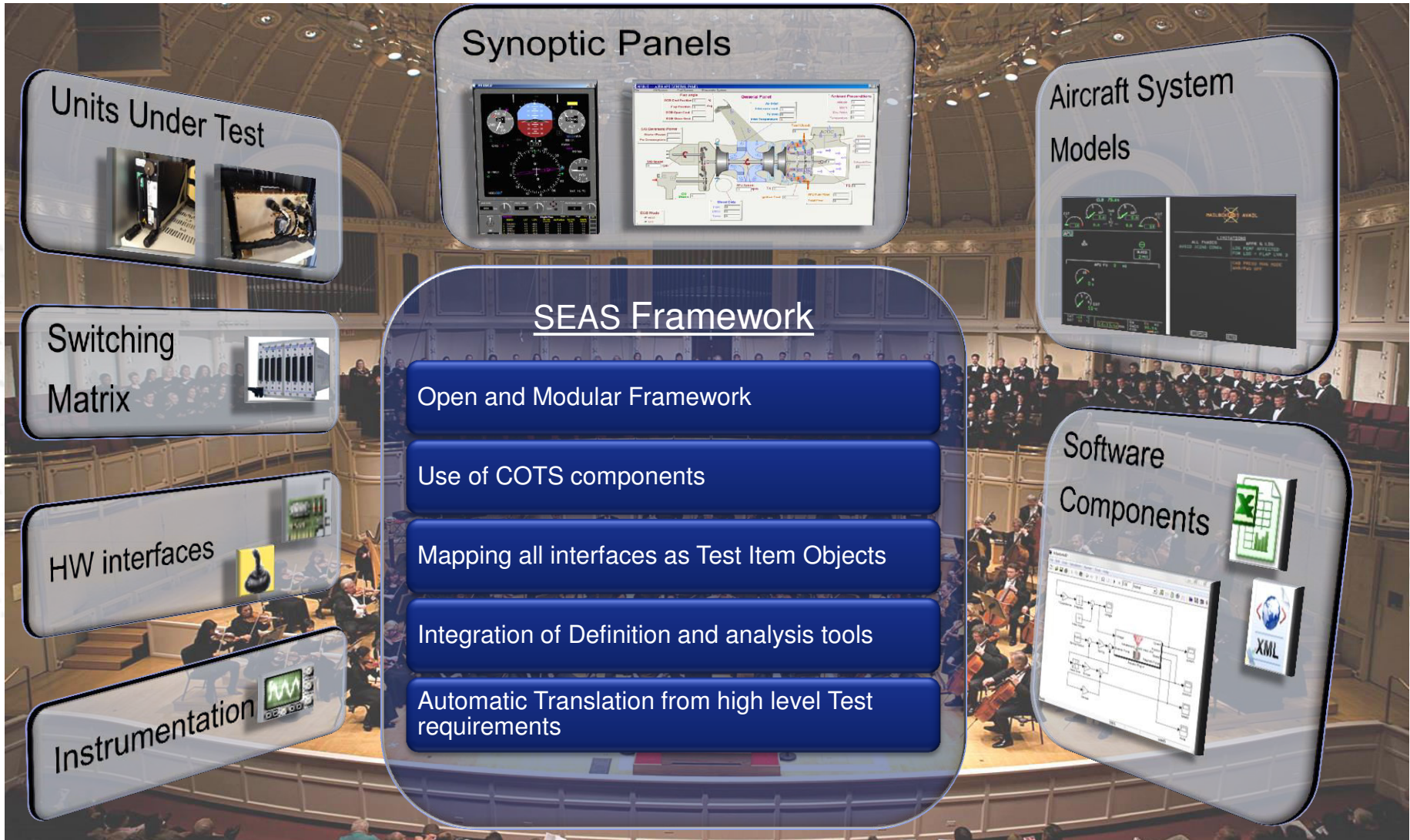
- The maturity, robustness and reliability of the system have been demonstrated throughout hundreds of test facilities in use with this common test environment, including Engineering Simulators for Aircraft Refuelling Boom System, System Integration Benches for Multirole Tanker Aircrafts, A400M, Light & Medium Transport Aircraft, Full Integrated Tactical Systems and Aircraft Interface Modules for Final Assembly Lines of A400M, Multirole Tanker Aircrafts and L&MT aircrafts.

- Proven with up to 400.000 signals per system integration bench

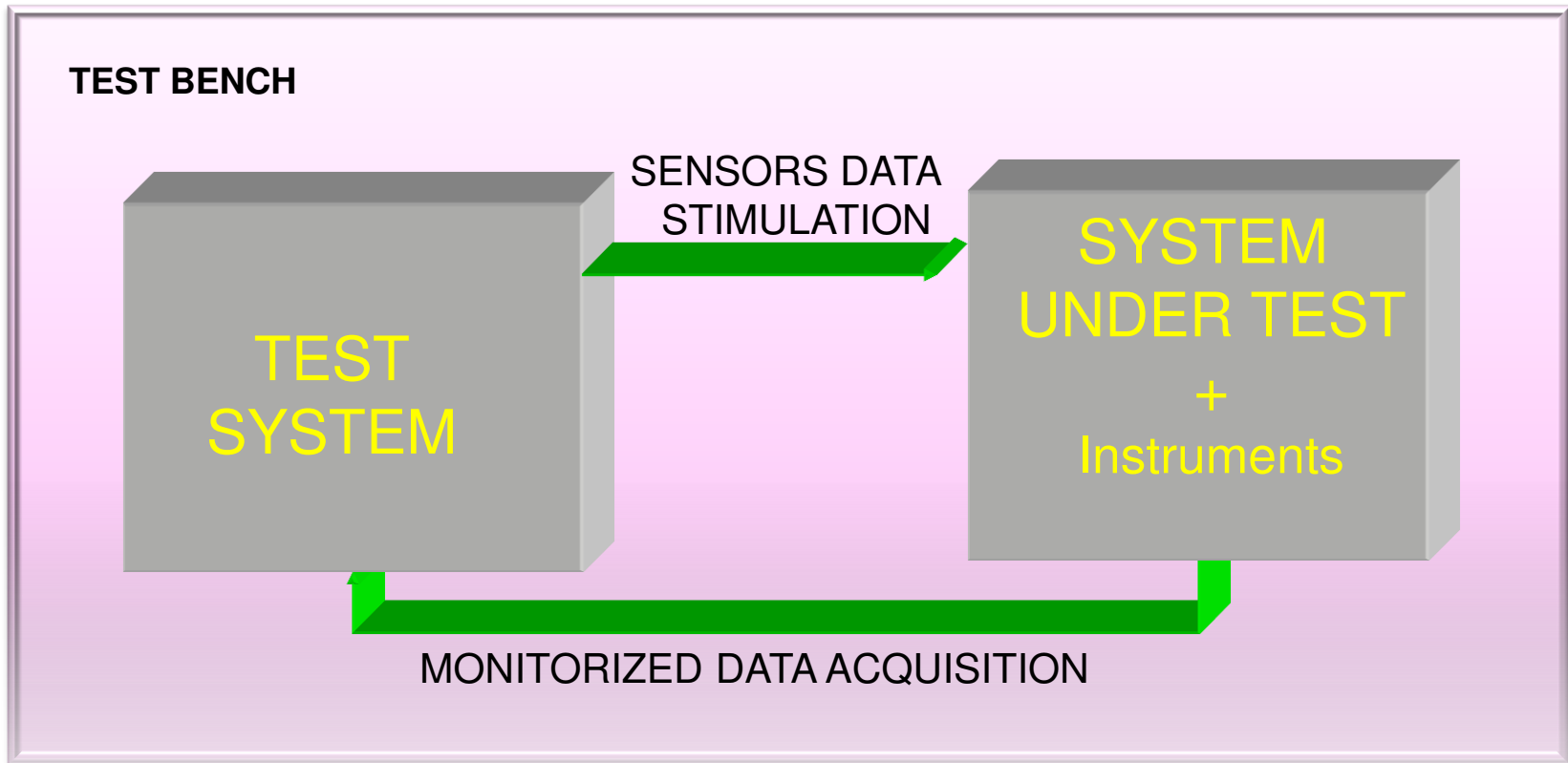
# Test Means Building and Operation using HW/SW bricks portfolio



# SEAS: The Orchestra Conductor



# SEAS Overview



## Stimulation, Acquisition and Simulation System (SEAS)

SEAS is a modular, generic, distributed set of HW/SW items used to build test facilities ( Engineering Simulator, SW Benches, Functional Test Benches and Target Rigs )

# SEAS Features

- Modular, open, distributed and scalable architecture widely used with minimal changes from desktop simulators to target rigs
- Key features: Configurability, Portability, Interoperability, Reusability, Scalability, Reliability and Maintainability
- **Generic SW components are written in Ada 95 / Ada 2005**
- SEAS Core SW: class-wide programming for Processes, Signals, HW Interfaces, Scaling, Processors, Testing Equipment ...
- “Factory Pattern”: deployment of distributed objects from the Central Objects Factory
- The backbone used to articulate components integration is based on two middleware solutions:
  - AdaCore GLADE / PolyORB with Ada DSA personality
  - SEASCOM (proprietary) network application protocol
- Thanks to the capability to flexibly exchange simulation models with real hardware SEAS can support the whole development lifecycle



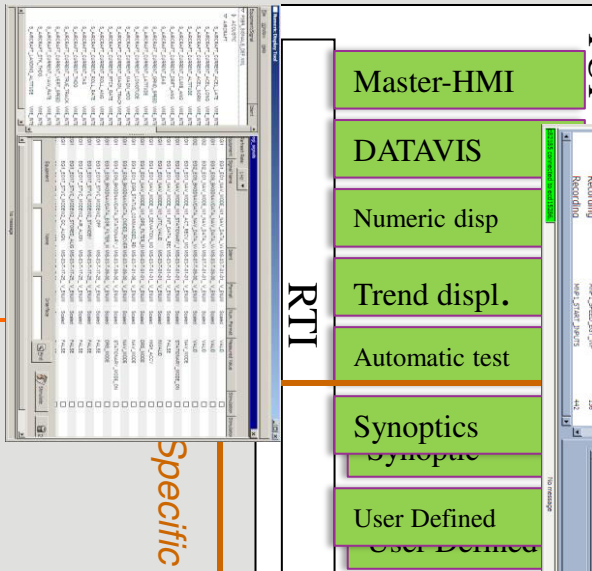
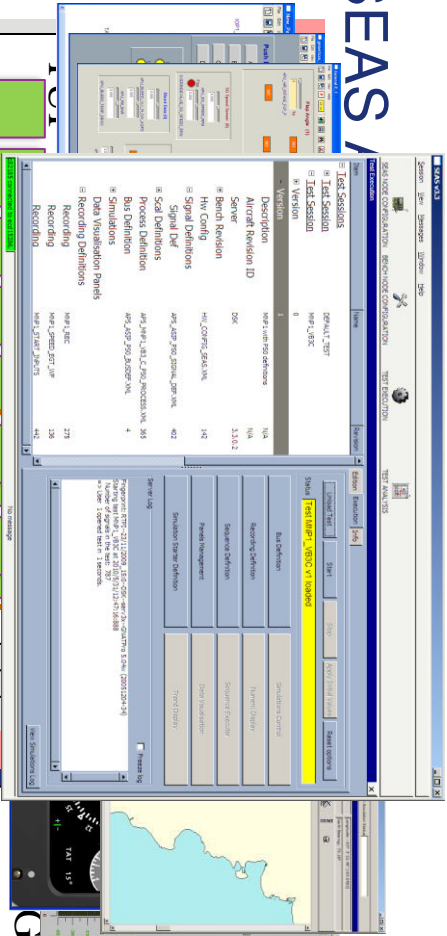
## SEAS Features (II)

- Simulation environment: multi-platform, multi-OS running in heterogeneous machines
- Multi-language support for simulations and bench specific SW  
(Ada, C, C++, Java, VB, FORTRAN, NI-LABVIEW, PYTHON...)
- HW access employs a flexible mechanism which makes it possible to connect it to internal variables belonging to a model, following the “Layer Pattern” where the connecting layer code is automatically generated
- Integration with COTS (commercial off-the-shelf) products:
  - industrial test tools by means flexible adapters
  - avionics and non-avionics I/F cards (A429, AFDX, 1553, EFEX, CAN, Analogue, Digital, Discrete, Ethernet, Shared Memory, High Speed data links)
  - HMI tools (GtkAda, VI, process control...)
  - multimedia products for realistic outside world 3D simulation

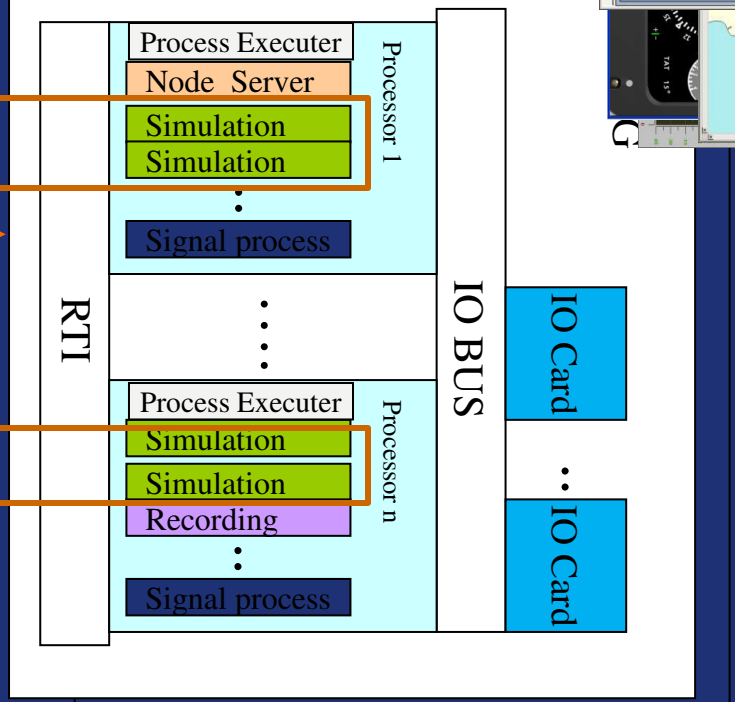
# A Test System built around AdaCore GNAT Pro Toolsuite

Our software development process is based on the AdaCore GNAT Pro Toolsuite. Its comprehensive set of tools include all the elements necessary to produce our test solution, including key features like support for distributed applications and multi-language integration:

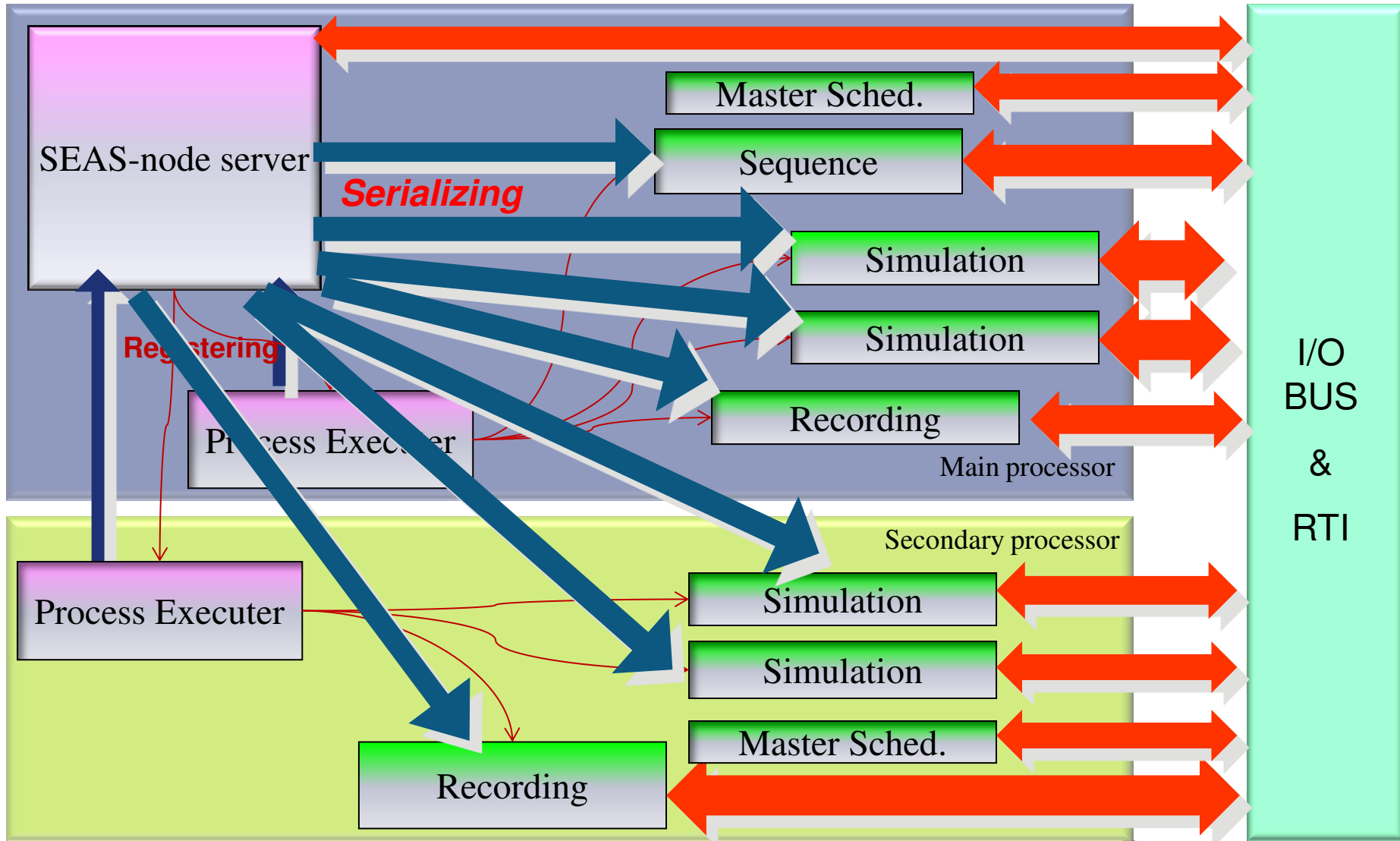
- **GNAT Pro's Integrated Development Environment** (GPS)
- **GNAT Pro Ada Compiler** (Ada 2012/2005/95/83)
- **GPRbuild**
- **GLADE, PolyORB/DSA**: Ada Distributed Systems Annex for shared memories, RPC, data, types and objects distribution
- **GPS Visual Debugger**
- **GNAT Libraries and Bindings** (POSIX API, Win32 API, ...)
- **GtkAda** for HMI and for special synoptic like mission scenarios, radar display simulations
- **XML/Ada Pro XML processing library** (supporting XML, SAX, DOM) for test system definitions, bench HW/SW definition



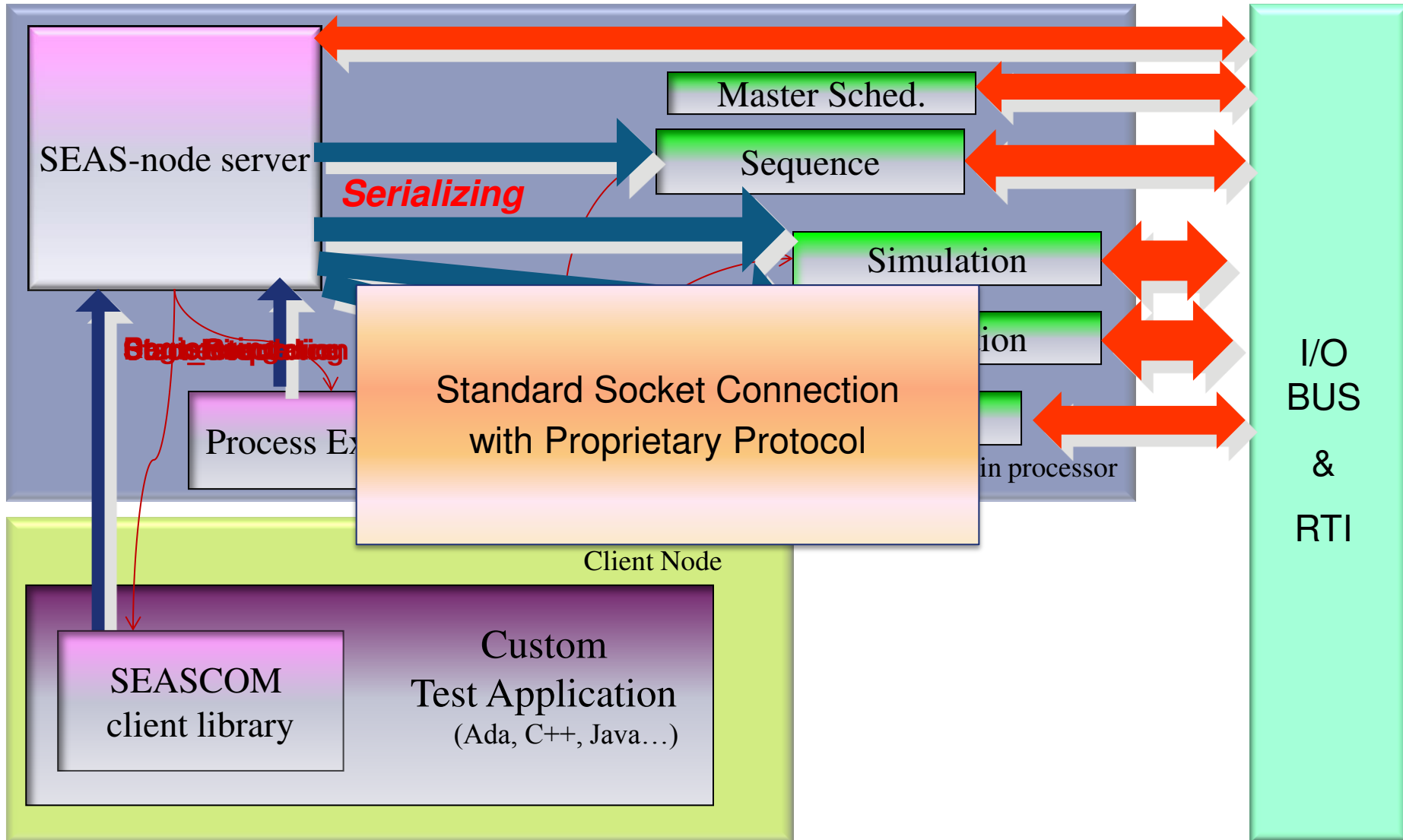
## Processing subsystem



# Signal Process Management



# SEASCOM Interface



# SEASCOM Interface (II)

The screenshot displays the SEASCOM development environment. At the top, a window titled 'GPS - TEMPLATE\_SIM\_main.adb - S:\Ada\_Seascomm\ - TEMPLATE\_SIM project' shows the IDE interface with a menu bar (File, Edit, Navigate, VCS, Project, Build, Debug, Tools, Window, Help) and a toolbar. Below it, a terminal window 'Z:\seas3\_server.exe' displays the message 'Seas license doesn't expire'. In the center, a Windows 'Administrador: Símbolo del sistema' window shows a directory listing of files and their sizes:

Date	Time	Size	Filename
12/05/2014	17:52	1.046	TEMPLATE_SIM.adb
13/05/2014	16:28	1.563	TEMPLATE_SIM.gpr
14/05/2014	16:28	27.490	TEMPLATE_SIM_main.adb
12/05/2014	17:52	91	TEMPLATE_SIM_main.ads
12/05/2014	17:52	12.762	TEMPLATE_SIM_NONSCHED_main.adb
13/05/2014	16:25	5.209	TEMPLATE_SIM_process.adb
12/05/2014	17:52	2.687	TEMPLATE_SIM_process.ads
12/05/2014	17:52	5.213	timer_manager.adb
12/05/2014	17:52	3.168	timer_manager.ads
		21 archivos	208.642 bytes

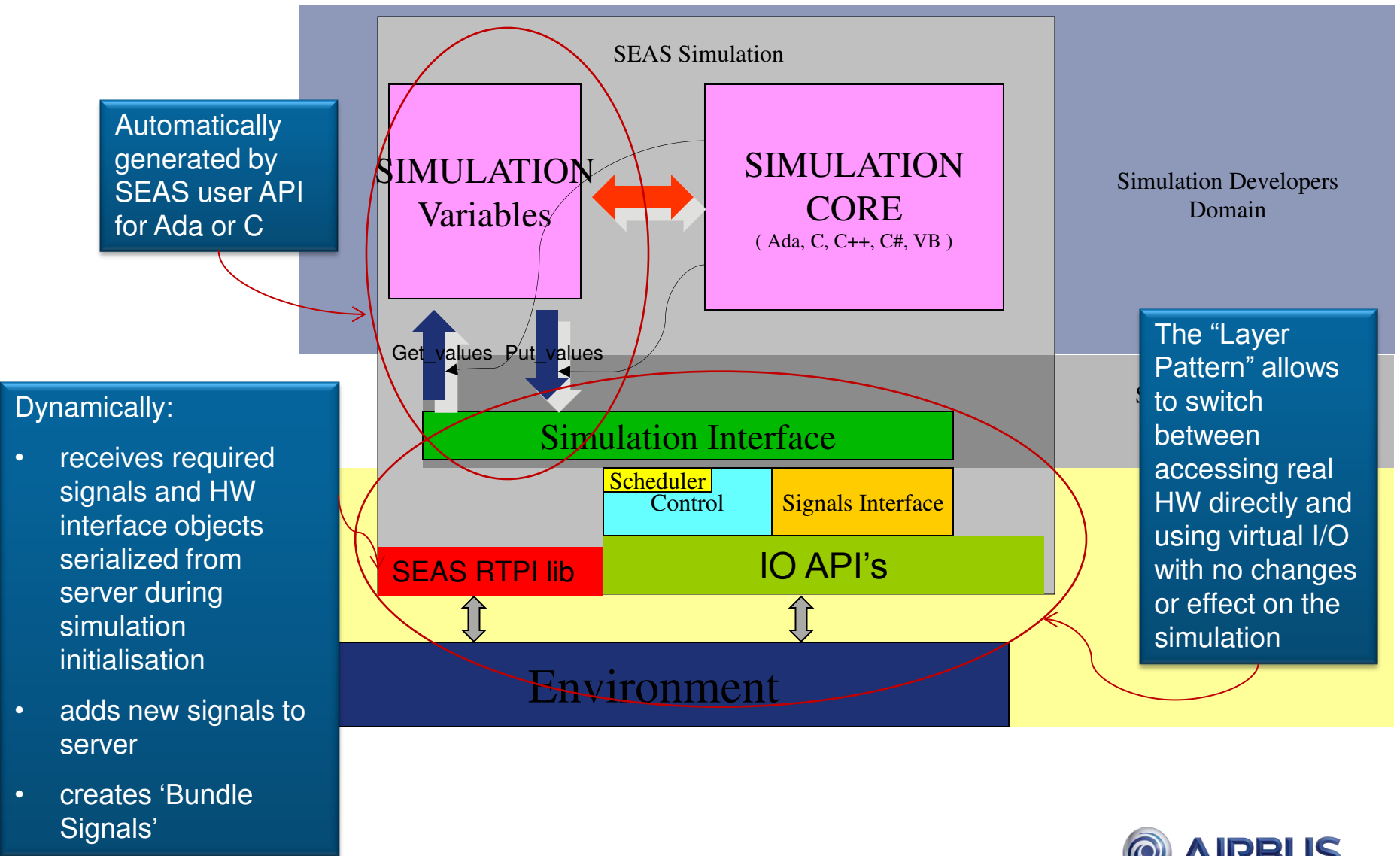
At the bottom, a terminal window 'Z:\process\_executer.exe' shows the following output:

```
Started process executer in node:  
Process_Executer registered successfully in server C:\Users\  
\seastmp  
Launched process SERU_INTERSIM_REC with PID 4344  
Terminating process with PID 4344
```

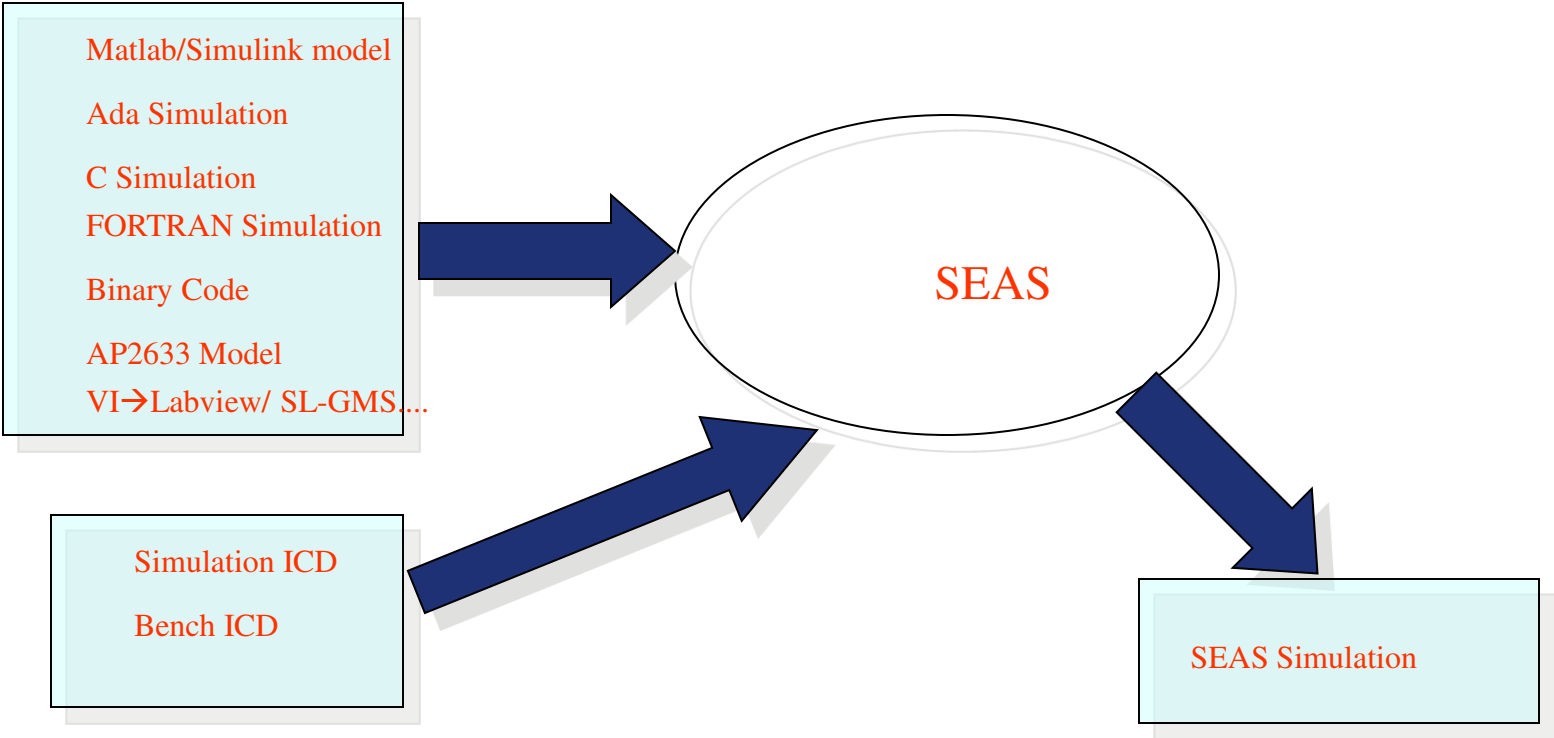
On the right side of the terminal windows, there is a partial view of code with the following lines:

```
RCI;"  
NOBJECT  
BJECT  
BJECT  
;"  
NOBJECT  
BJECT
```

# SEAS Simulations Layers



# Simulations Build





Associate Bench signals

The screenshot displays the GPS-GNAT programming studio interface. The top portion shows a stack of open Ada files, including `simple_epdc_main.adb`, `signal_process-simulation.adb`, `simple_epdc_process.ads`, `simple_epdc_interf.ads`, and `simple_epdc_interf.adb`. The main window shows the `simple_epdc_interf.adb` file with an outline view on the left and the source code on the right. The outline view lists various packages and procedures, such as `A429_SORT_TYPE`, `A429_SPEED_TYPE`, `ARINC_CHANNEL_TYPE`, and `A429_ADD_ASYNC_CMD_BLK`. The source code on the right includes a function `a429_init_filter_table` and a procedure `A429_Get_Channel_Address`. A yellow highlight is placed over the text "Binding package to COTS API's given in C or C++". The bottom of the window shows a console window with the message "Loading font-lock...done".

Binding package to COTS API's given in C or C++

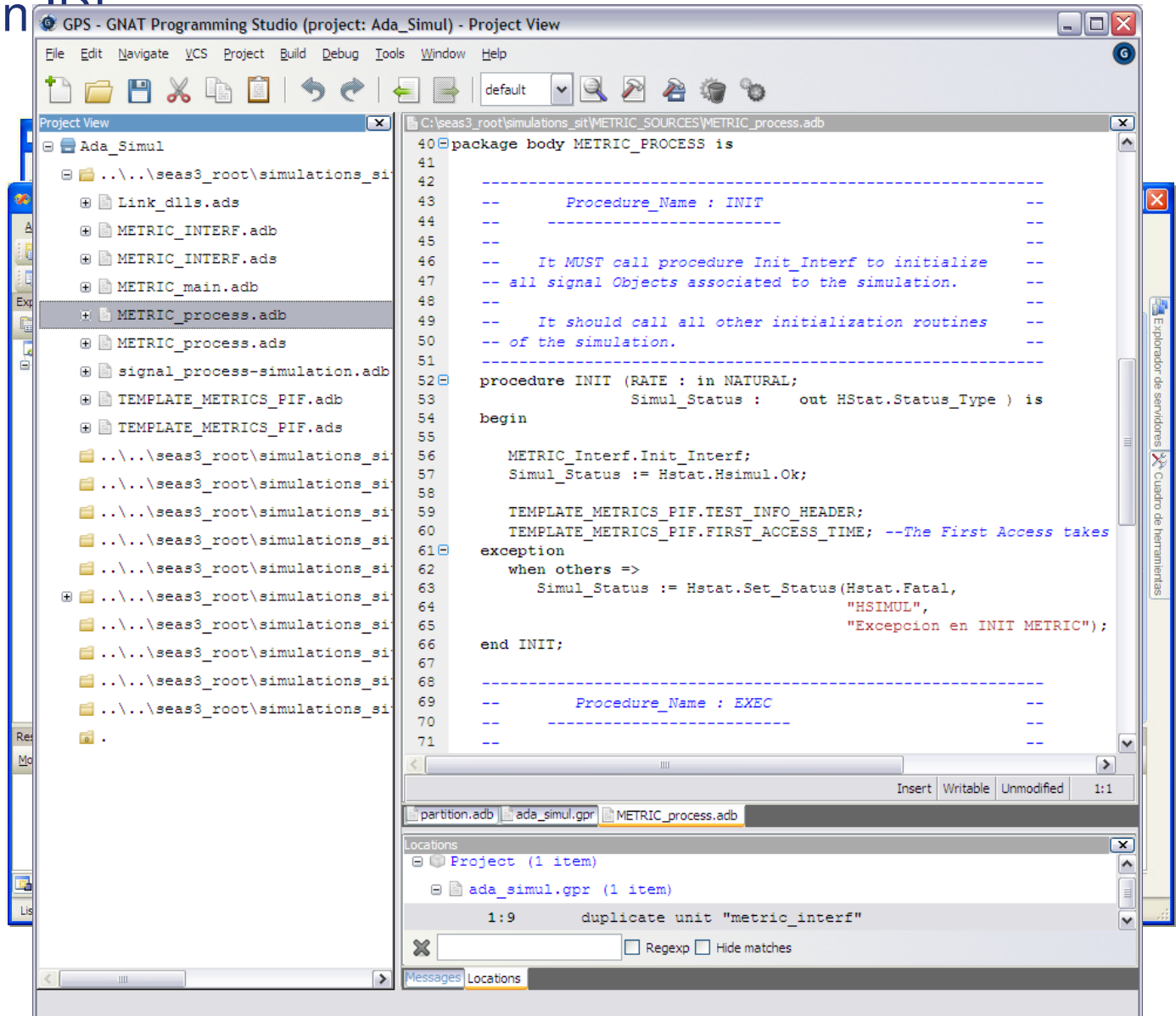


# SEAS Simulation IDE

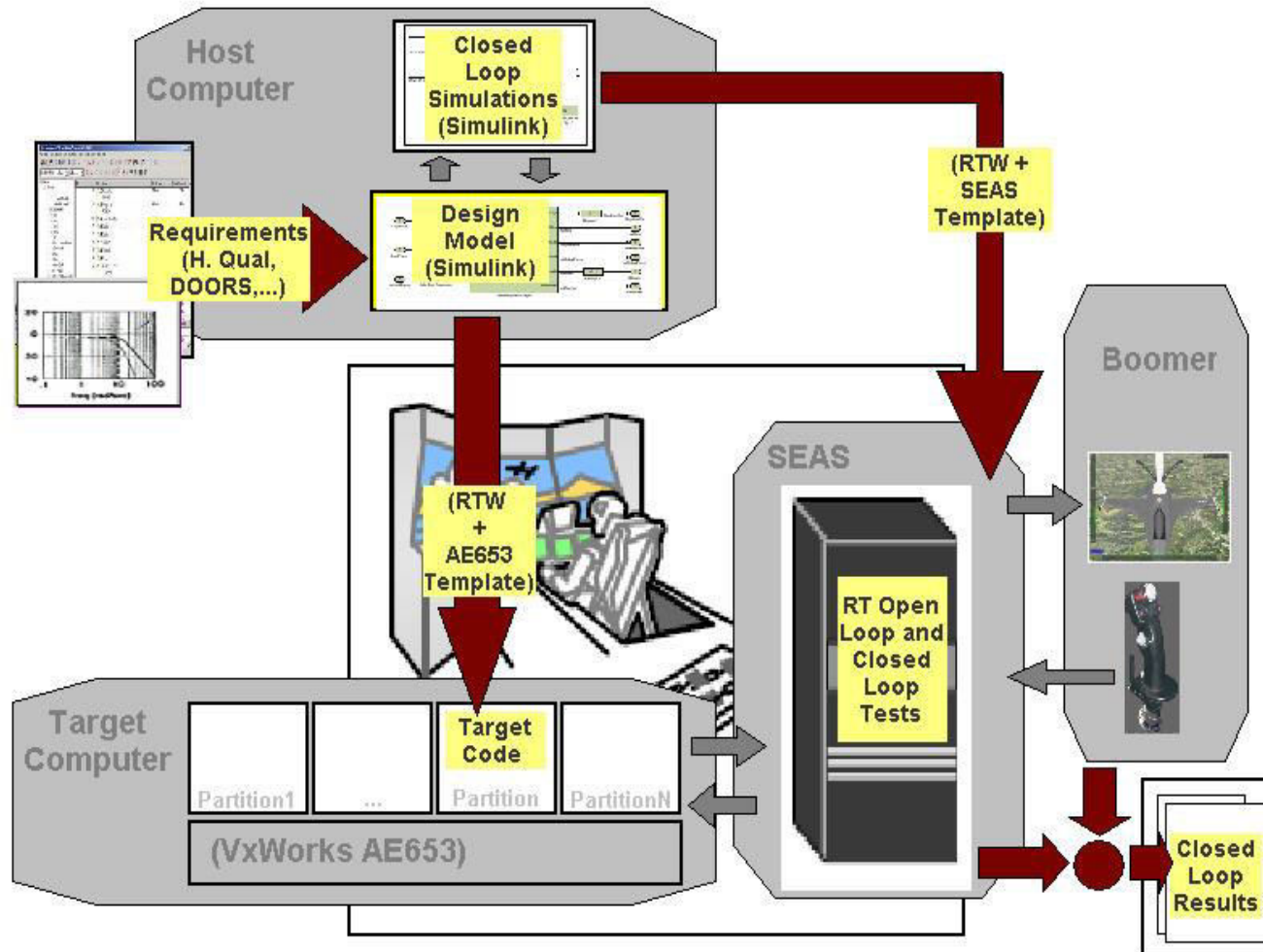
SEAS connected to native IDE for simulations and specific test tools

For Ada and C Code, generating a GPS project and launching GPS

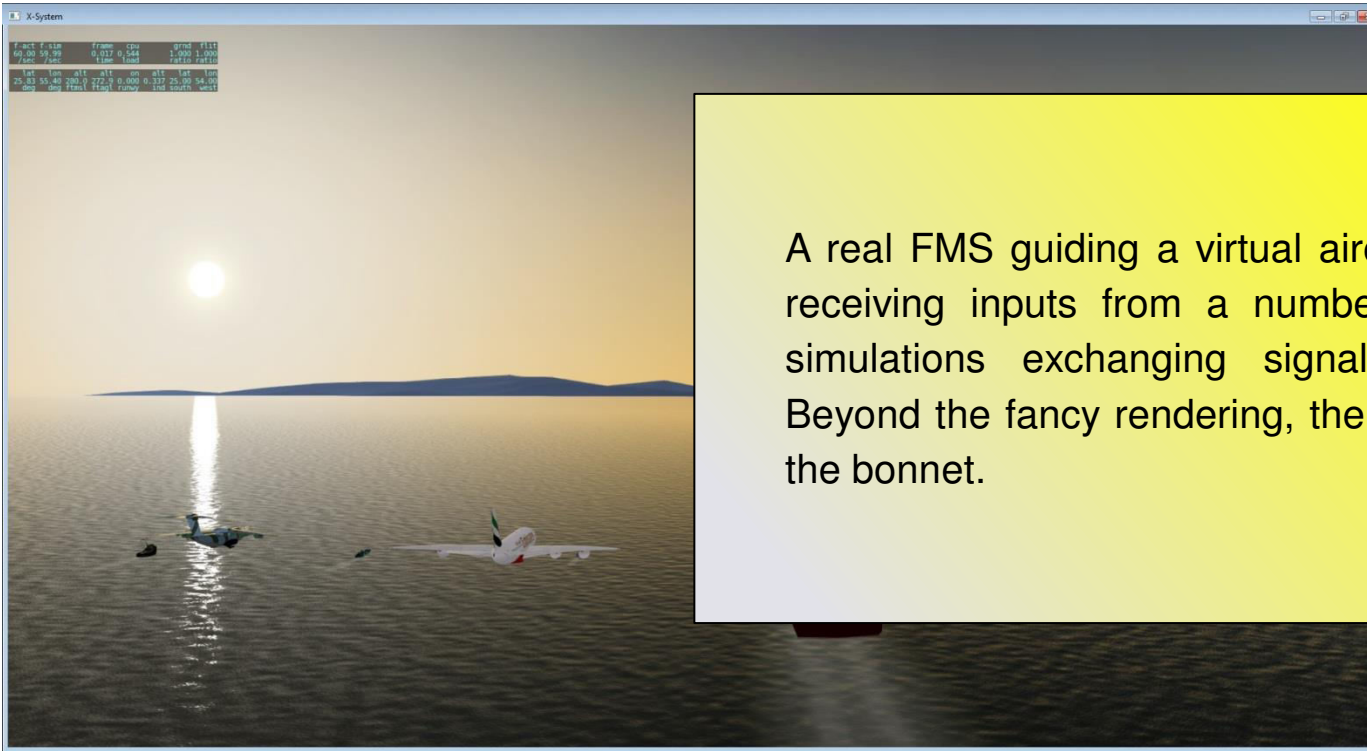
... Or for Visual C source code, generating a Visual C project and launching Visual Studio Application



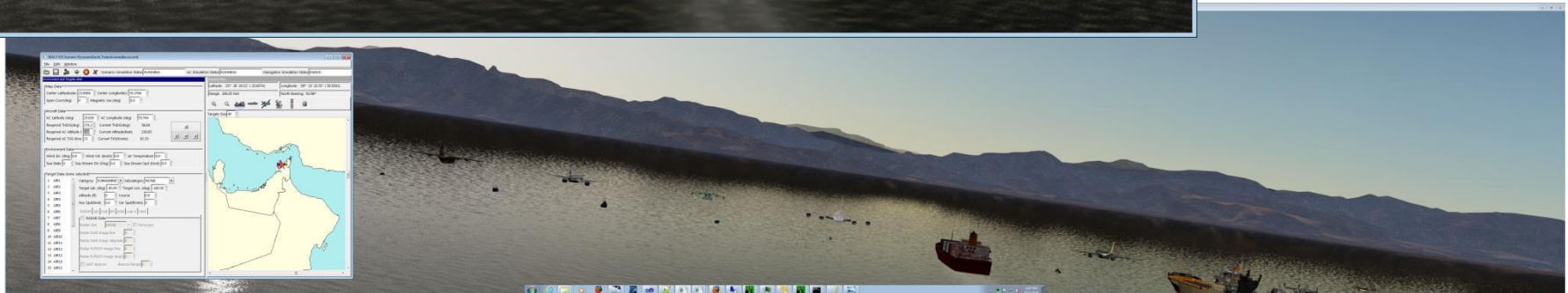
# Tools Integration: Matlab Simulink models to SEAS Route ARBS application



# Tools Integration: Integration with realistic 3D modelling tools



A real FMS guiding a virtual aircraft on autopilot, receiving inputs from a number of coordinated simulations exchanging signals in real time. Beyond the fancy rendering, there is SEAS under the bonnet.



# Summary

- Our testing solution, SEAS, makes extensive use of Ada with the goal of providing a comprehensive solution to most testing needs throughout the development life cycle of aircraft on-board electronics equipment at Airbus Defence and Space, Military Aircraft
- Test System built around AdaCore GNAT Pro Toolsuite
- Ada 95 / 2005 for SEAS Core SW using class wide programming
- Ada 95 / 2005 for simulations, possibly in combination with many other languages
- GtkAda for HMI, among other solutions
- XML / Ada for data file processing
- Ada Distributed Systems Annex for shared memories, RPC, data, types and objects distribution
- Patterns: “Factory Pattern”, “Central Objects Factory”, “Layer Pattern”
- Future developments aimed at widening the scope of interoperability with third-party products by means of open, standard protocols

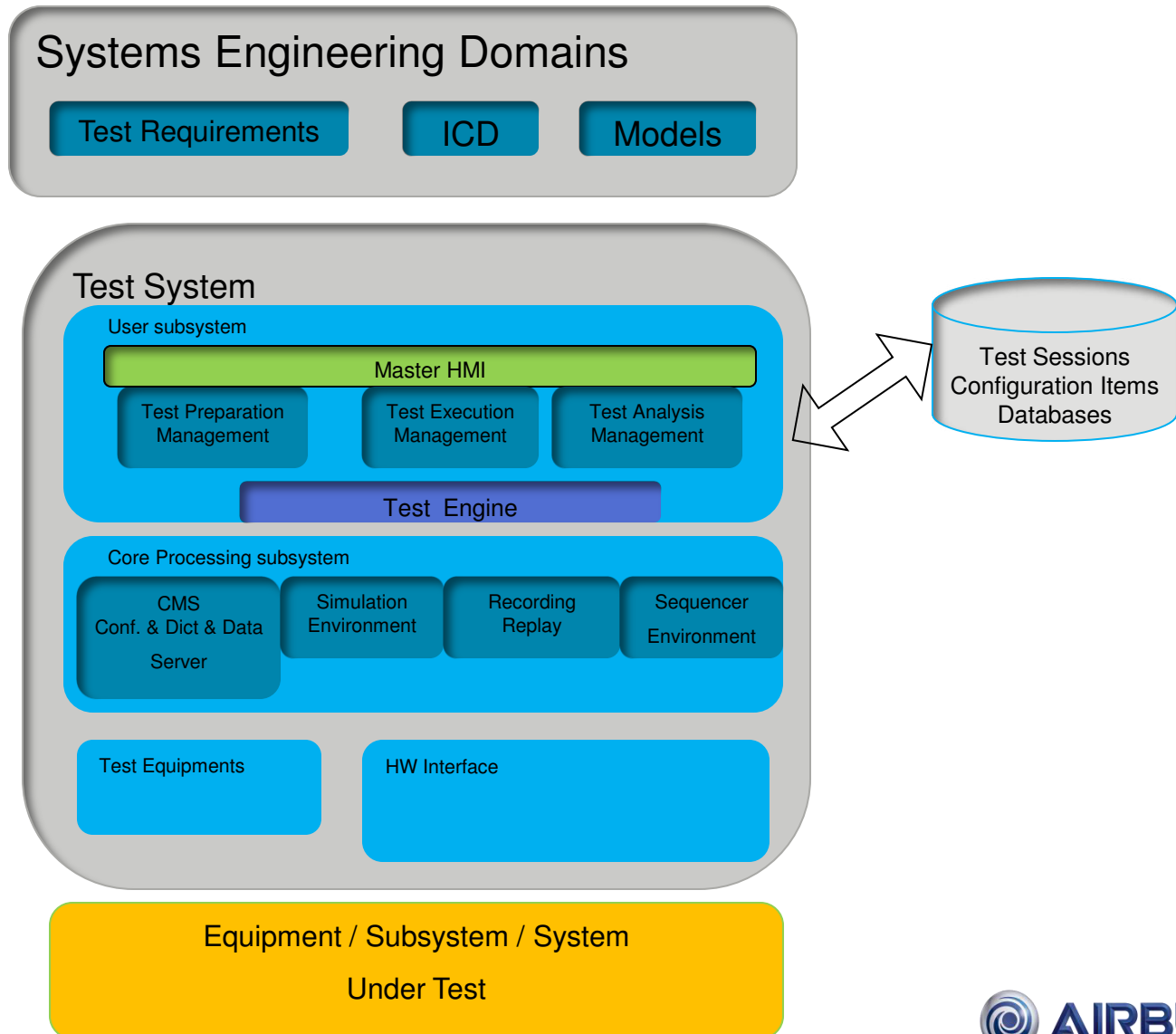
*Thank you for your attention*

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## Support slides

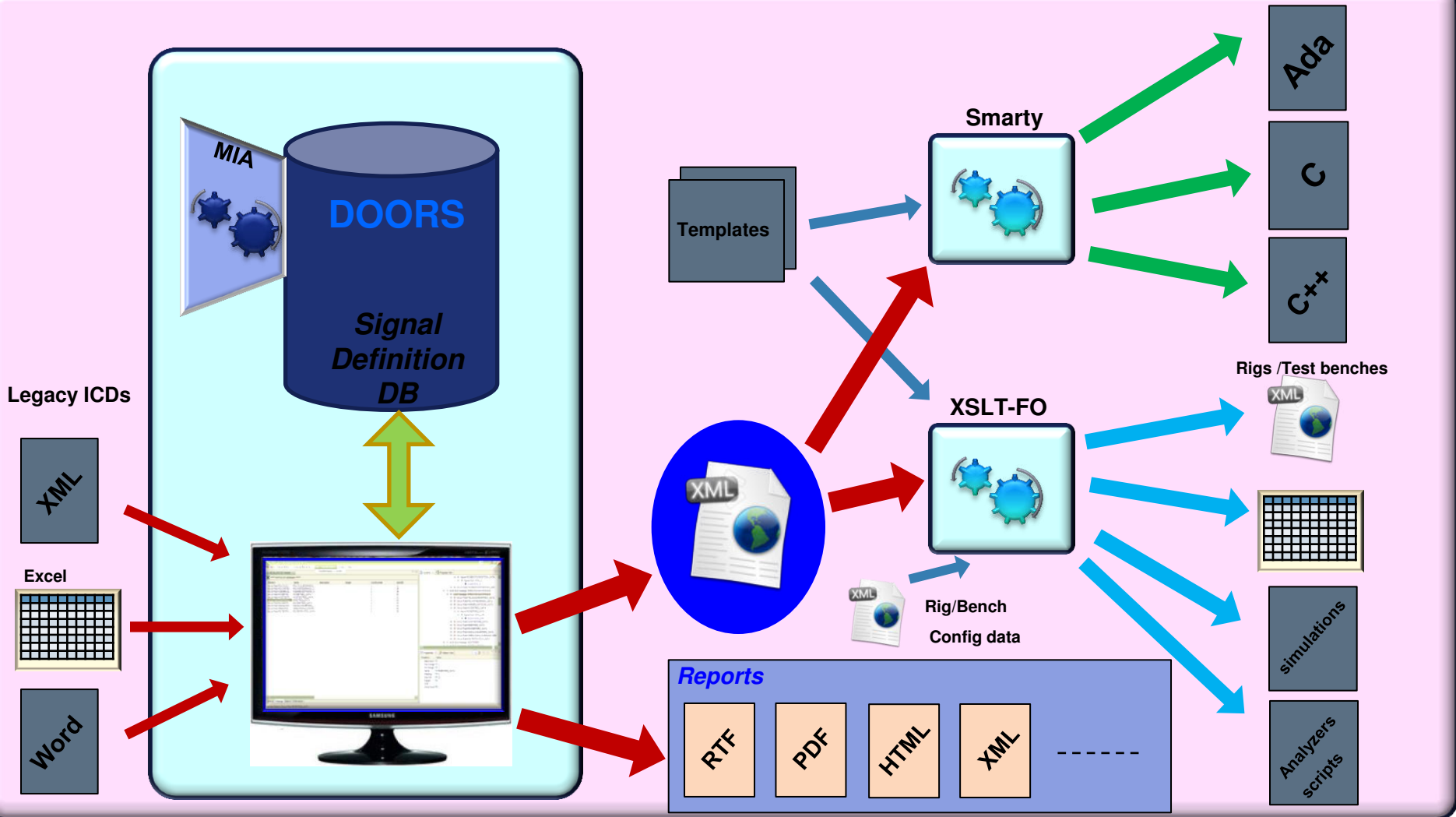
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# SEAS Context Diagram

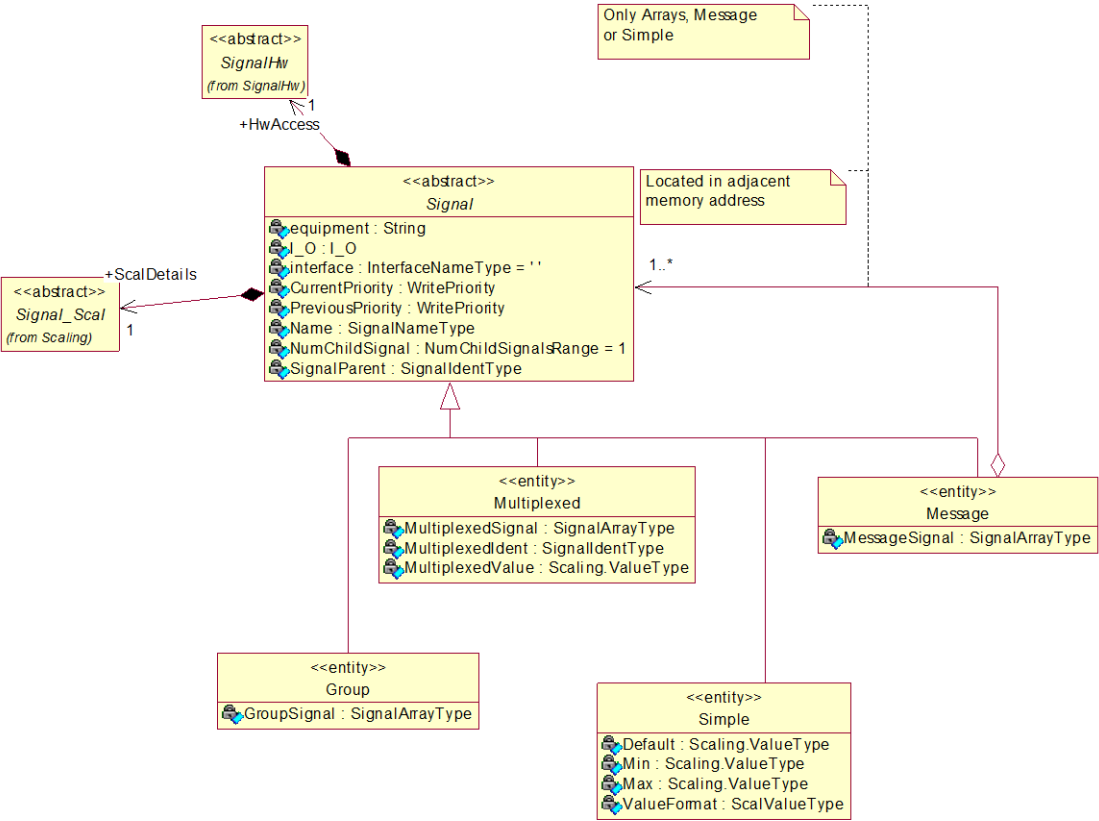




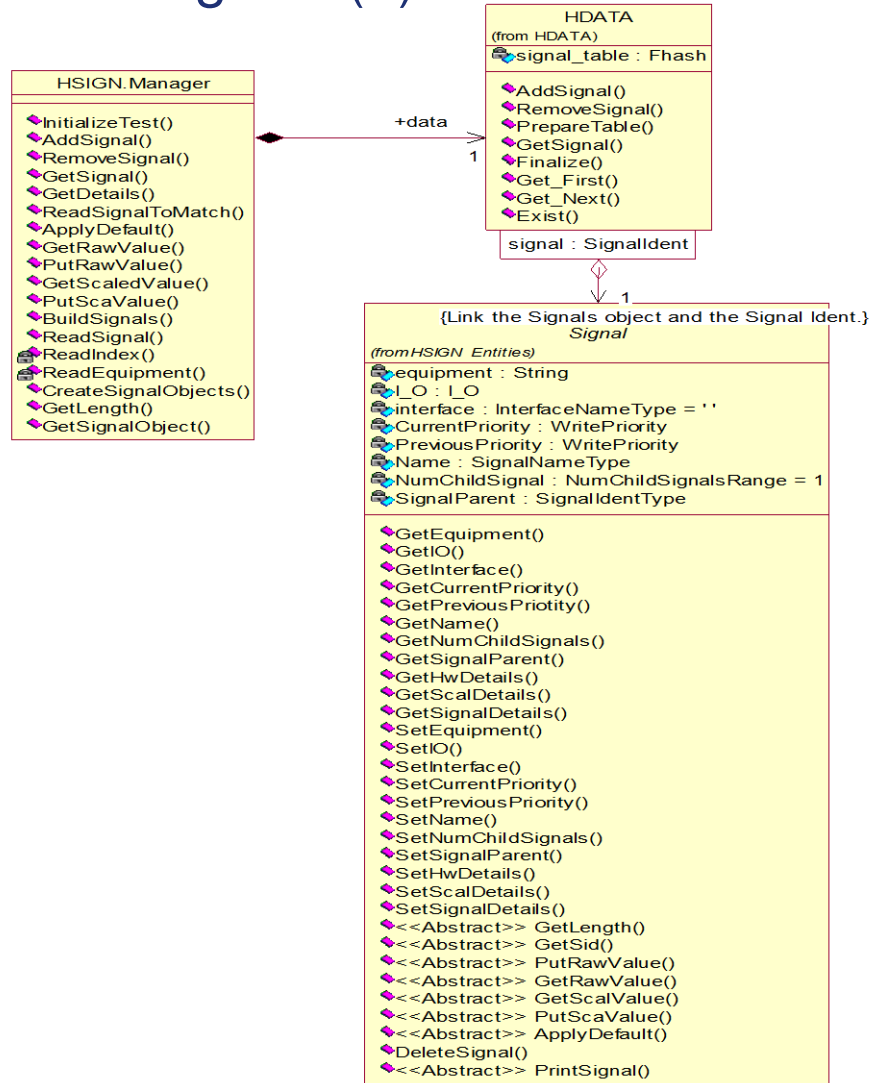
# A/C ICD's Management



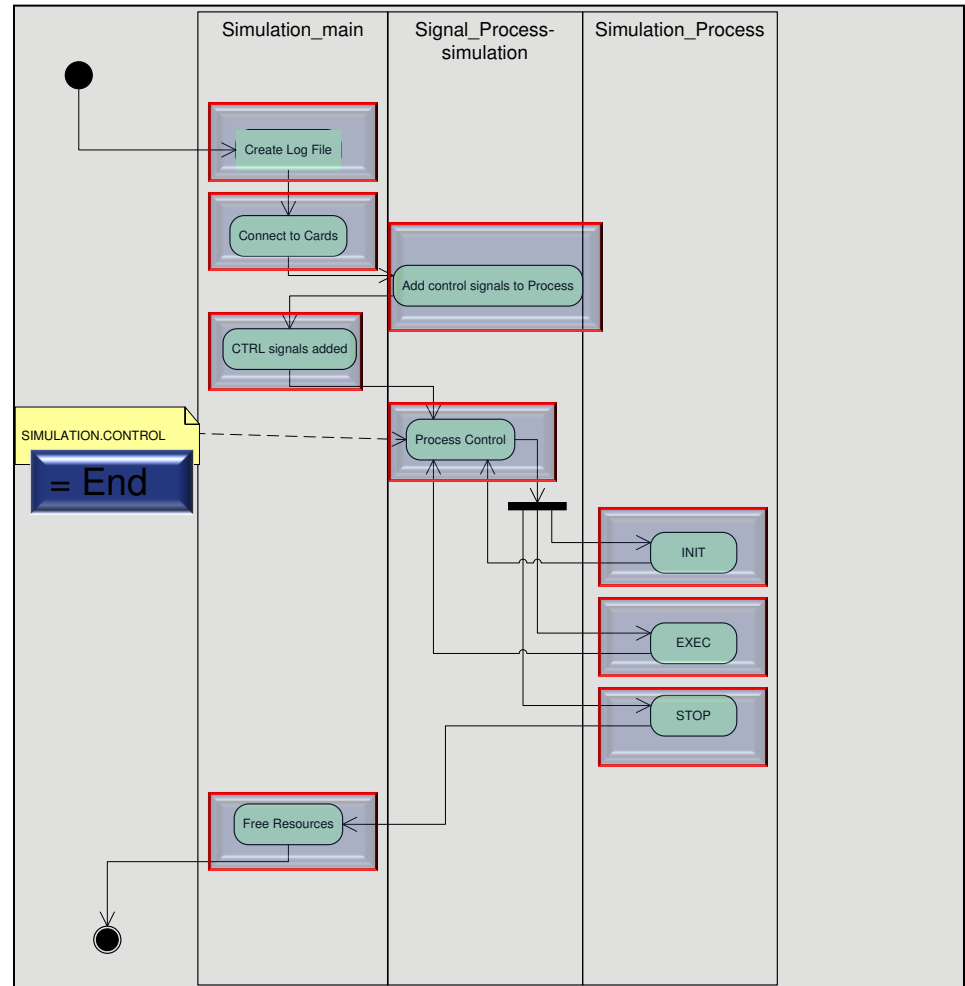
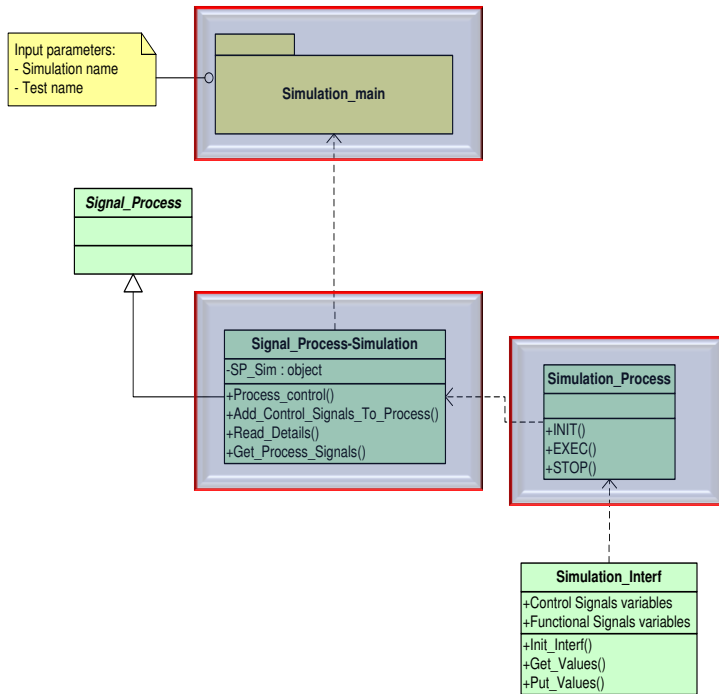
# SEAS Signal Class Diagram



# SEAS Signal Class Diagram (II)



# SEAS Simulation Class and Activity Diagram



# PolyORB

Middleware implementation providing development tools and an innovative runtime library architecture for collaboration of application components using open standards for distributed systems.

PolyORB is a middleware toolset that provides distribution services through standard programming interfaces (e.g. CORBA, the Ada Distributed Systems Annex, or the MOMA messaging API) and communication protocols (e.g. GIOP and SOAP). It addresses distribution model interoperability issues by allowing a single middleware instance to efficiently support multiple personalities executing simultaneously. Its modular architecture emphasizing code reuse allows the definition and deployment of middleware configurations that are specially adapted for real-time, high integrity applications.

## Ada Distributed Systems Annex (DSA)

The Ada Distributed Systems Annex allows easy creation and deployment of distributed applications using standard language features. The construction of a distributed application is facilitated by leveraging on existing Ada constructs to identify distributed component boundaries and interfaces. Applications can be written as though not distributed, and later on partitioned into multiple subsets assigned to distinct nodes, and communicating through remote subprogram calls and shared data.

The PolyORB/DSA implementation includes:

- a distribution stubs generator, included in the GNAT Pro compiler;
- GNATDIST: a partitioning tool allowing the generation of executable images for each partition in a DSA distributed application
- a PCS (Partition Communication Subsystem) implemented as personality modules within the PolyORB framework, providing runtime communication services and distribution support to application components.